

**Amendments to the Abstract:**

Please substitute the following version of the Abstract, with changes shown by strikethrough (for deletions) or underlining (for added matter).

ABSTRACT OF THE DISCLOSURE

~~The invention relates to an~~ An object handling method ~~which consists of~~ for determining the positions of the arm of a handling system with the aid of a location method which is based on a reference system predetermined by an associated location system. ~~The inventive device for carrying out the method is also disclosed.~~ A handling system having a moveable arm. The arm is operational within a fixed reference system using a location system.